

Review:

Curve is geodesic: $\ddot{\gamma}$ always \perp to tangent plane (ie parallel to \vec{N})

- Facts:
- ① Geodesics have constant speed
 - ② Geodesics have $K_g = 0$ (zero geod. curvature)
 - ③ Straight lines + normal sections are geodesic.
 - ④ Geodesics are preserved by isometries
 - ⑤ For each pt $P \in \Sigma$ and tangent $\vec{T} \in T_p\Sigma$, there is a geodesic thru P w/ tangent \vec{T} .

Geodesic Eqns:

$$\begin{cases} \frac{d}{dt}(Eu + F\dot{v}) = \frac{1}{2}(E_u \dot{u}^2 + 2F_u \dot{u}\dot{v} + G_u \dot{v}^2) \\ \frac{d}{dt}(F\dot{u} + G\dot{v}) = \frac{1}{2}(E_v \dot{u}^2 + 2F_v \dot{u}\dot{v} + G_v \dot{v}^2) \end{cases} \quad (*)$$

Unit-Speed Conditions:

$$E\dot{u}^2 + 2F\dot{u}\dot{v} + G\dot{v}^2 = 1 \quad (**)$$

8.3 Sfc. of Revol. $\vec{\sigma}(u,v) = \langle f(u)\cos v, f(u)\sin v, g(u) \rangle \Rightarrow \mathbb{F}_I = du^2 + f(u)^2 dv^2$ p.125
 $(\| \langle f, g \rangle \| = 1, f > 0)$
 $\begin{matrix} \uparrow & \uparrow & \uparrow \\ E=1 & F=0 & G=f(u)^2 \end{matrix}$

So (*) becomes $\ddot{u} = \frac{1}{2}(0+0+2F\frac{d}{du}\dot{v}^2) = f(u)\frac{d}{du}\dot{v}^2$ (D) becomes $\dot{u}^2 + f(u)^2\dot{v}^2 = 1$ (C)
 $\frac{d}{dt}(f(u)^2\dot{v}) = 0$ (B)

So (i) every meridian ($v = \text{const.}$) is geodesic... bc $\dot{v} = 0 \Rightarrow$ (B) true, $\dot{u}^2 = 1 \Rightarrow \ddot{u} = 0 \Rightarrow$ (A) true.

(ii) parallel is geodesic iff $\frac{df}{du} = 0$, ie. u_0 is "stationary pt" of f .

bc (A) means $f(u_0)\frac{d}{du}\dot{v}^2 = 0$, (C) means $f(u_0)^2\dot{v}^2 = 1 \Rightarrow \frac{df}{du} = 0$.
 But $\dot{v} = \pm 1/f(u_0) = \text{const}$ so (B) is true. ✓

Clairaut's Thm: If ρ is distance from pt to axis of rotation, ψ is true angle between a geodesic γ and the meridians, then $\rho \sin \psi$ is constant along γ .
 Conversely, $\rho \sin \psi$ and no overlap of a parallel implies geodesic.

Proof: ~~$\rho = f(u)$~~ $\rho = f(u)$, and the tangent space is spanned by $\frac{\vec{\sigma}_u}{\|\vec{\sigma}_u\|} = \vec{\sigma}_u$ and $\frac{\vec{\sigma}_v}{\|\vec{\sigma}_v\|} = \frac{1}{\rho}\vec{\sigma}_v$, which are perp. unit vectors.

So for $\dot{\gamma}$ unit-speed, $\dot{\gamma} = \cos \psi \vec{\sigma}_u + \frac{1}{\rho} \sin \psi \vec{\sigma}_v \Rightarrow \vec{\sigma}_u \times \dot{\gamma} = \frac{1}{\rho} \sin \psi \vec{\sigma}_u \times \vec{\sigma}_v$
 or $\vec{\sigma}_u \times (\dot{u}\vec{\sigma}_u + \dot{v}\vec{\sigma}_v) = \dot{v}\vec{\sigma}_u \times \vec{\sigma}_v = \frac{1}{\rho} \sin \psi \vec{\sigma}_u \times \vec{\sigma}_v$
 $\Rightarrow \dot{v} = \frac{1}{\rho} \sin \psi$

Now $\frac{d}{dt}(\rho^2 \dot{v}) \stackrel{(B)}{=} \frac{d}{dt}(\rho \sin \psi) = 0 \Rightarrow \rho \sin \psi = \text{constant}$. ✓

Conversely, if $\rho \sin \psi = \delta$ then $\dot{v} = \frac{\delta}{\rho^2}$, $\dot{u}^2 = 1 - \frac{\delta^2}{\rho^2} \Rightarrow 2\dot{u}\ddot{u} = \frac{2\delta^2}{\rho^3} \dot{\rho} = \frac{2\delta^2}{\rho^2} \frac{d\rho}{du} \dot{u}$
 so that $\dot{u}(\ddot{u} - \rho \frac{d\rho}{du} \dot{v}^2) = 0$

Since $\dot{u} \neq 0$ in any interval, must have $\ddot{u} = \rho \frac{d\rho}{du} \dot{v}^2$ implying (A). ■

Ex: Pseudosphere $\tilde{\sigma}(u,v) = \langle e^u \cos v, e^u \sin v, \sqrt{1-e^{2u}} - \cosh^{-1}(e^u) \rangle$, $\mathcal{F}_I = du^2 + e^{2u} dv^2$.
 \rightarrow reparam $w = e^u$ $\tilde{\sigma}(v,w) = \langle \frac{1}{w} \cos v, \frac{1}{w} \sin v, \sqrt{1-\frac{1}{w^2}} - \cosh^{-1}(w) \rangle$, $\mathcal{F}_I = \frac{1}{w^2} (dv^2 + dw^2)$

Require $w > 1$ for smoothness.

Unit speed geodesic $\Rightarrow \dot{v}^2 + \dot{w}^2 = w^2$

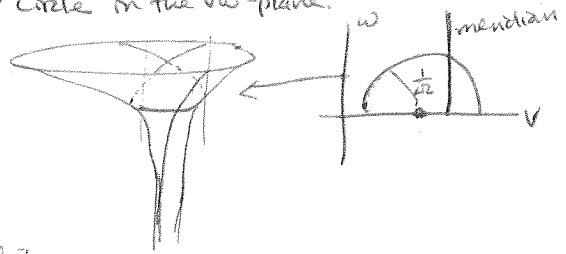
Clairaut's Thm $\Rightarrow \frac{1}{w} \sin \psi = \frac{1}{w} \dot{v} = \Delta_0$ since $\rho = \frac{1}{w}$. So $\dot{v} = \Delta_0 w^2$.

For $\Delta_0 = 0$: get meridian $v = \text{constant}$.

For $\Delta_0 \neq 0$: get $\dot{w} = \pm w \sqrt{1 - \Delta_0^2 w^2}$ so $\frac{dw}{w} = \pm \frac{\Delta_0 w}{\sqrt{1 - \Delta_0^2 w^2}}$ and integrate $v - v_0 = \mp \frac{1}{\Delta_0} \sqrt{1 - \Delta_0^2 w^2}$.

Thus $(v - v_0)^2 + w^2 = \frac{1}{\Delta_0^2} \Leftrightarrow$ circle in the vw -plane.

Since $\rho = \frac{1}{w}$, implies geodesic has $\frac{1}{\rho} \leq \frac{1}{\Delta_0}$ or $\rho \geq \Delta_0$, so is ~~outside~~ ^{outside} to cylinder about axis of radius Δ_0 .



In general: Clairaut's implies $\rho \sin \psi = \Delta_0 \leftarrow$ call it angular momentum.

Assume positive angles, i.e. $\Delta_0 > 0$.

Then $\dot{u}^2 = 1 - \frac{\Delta_0^2}{\rho^2}$ implies $\rho \geq \Delta_0$ in general, i.e. contained ^{outside} cylinder of radius Δ_0 .

Without equality somewhere, $\dot{u} > 0$ everywhere and the geodesic crosses all parallels.

Ex: Hyperboloid:

