

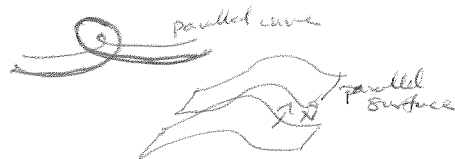
7.4

Suppose $H = \frac{1}{2}(K_1 + K_2)$ is constant \iff minimal surfaces.
 (because variation of sfc. area can be written as an integral over H)

$$= \frac{LG - 2MF + NE}{2(EG - F^2)}$$

 any sfc. minimizing area for a given boundary is a minimal sfc.

Def: Given $\vec{\sigma}$ patch, $\vec{\sigma}^\lambda = \vec{\sigma} + \lambda \vec{N}$ is a parallel surface



Prop: Spse. $|k_1|, |k_2| \leq C$ everywhere.

Let λ be constant s.t. $|\lambda| < \frac{1}{C}$ everywhere. Then

- (i) $\vec{\sigma}^\lambda$ is a reglar sfc. patch
- (ii) $\vec{N}^\lambda = \vec{N}$ $\forall (u, v)$... same normals
- (iii) Principal curvatures are $\frac{k_1}{1-\lambda k_1}, \frac{k_2}{1-\lambda k_2}$
- (iv) $K^\lambda = K(1-2\lambda H + \lambda^2 K)^{-1}$
 $H^\lambda = (H - \lambda K)(1-2\lambda H + \lambda^2 K)^{-1}$

Keeps surface from self intersections.

Def: $\vec{\sigma}_u^\lambda = \vec{\sigma}_u + \lambda \vec{N}_u = (1 + \lambda a) \vec{\sigma}_u + \lambda b \vec{\sigma}_v$...
 $\vec{\sigma}_v^\lambda = \vec{\sigma}_v + \lambda \vec{N}_v = \lambda c \vec{\sigma}_u + (1 + \lambda d) \vec{\sigma}_v$... where $\mathcal{W} = \begin{pmatrix} a & c \\ b & d \end{pmatrix}$
 $\implies \vec{\sigma}_u^\lambda \times \vec{\sigma}_v^\lambda \parallel \vec{\sigma}_u \times \vec{\sigma}_v$ so $\vec{N}^\lambda = \vec{N}$

In particular $\vec{\sigma}_u^\lambda \times \vec{\sigma}_v^\lambda = (1 - \lambda k_1)(1 - \lambda k_2) \vec{\sigma}_u \times \vec{\sigma}_v$... and the constants $|\lambda k_1|, |\lambda k_2| < 1$ so this is nonzero \implies regular

We have $\begin{pmatrix} N_u^\lambda \\ N_v^\lambda \end{pmatrix} = -\mathcal{W} \begin{pmatrix} \sigma_u^\lambda \\ \sigma_v^\lambda \end{pmatrix} = -\mathcal{W}^\lambda \begin{pmatrix} \sigma_u \\ \sigma_v \end{pmatrix} = -\mathcal{W}^\lambda \begin{pmatrix} \sigma_u \\ \sigma_v \end{pmatrix} + \lambda \begin{pmatrix} N_u \\ N_v \end{pmatrix} = -\mathcal{W}^\lambda \begin{pmatrix} \sigma_u \\ \sigma_v \end{pmatrix} + \lambda \begin{pmatrix} N_u \\ N_v \end{pmatrix}$

$\implies -\mathcal{W} = -\mathcal{W}^\lambda (I - \lambda \mathcal{W}) \implies \mathcal{W}^\lambda = \mathcal{W} (I - \lambda \mathcal{W})^{-1}$

So evals. of \mathcal{W} are evals of $I - \lambda \mathcal{W}$, hence evals of \mathcal{W}^λ , and $k \mapsto \frac{k}{1 - \lambda k}$.

Cor: If H is constant, $\lambda = \frac{1}{2H}$, then $\vec{\sigma}^\lambda$ has constant Gaussian curvature $4H^2$.
 Conversely, if $\vec{\sigma}$ has constant Gaussian curvature K , then for $\lambda = \frac{\pm 1}{\sqrt{K}}$, $\vec{\sigma}^\lambda$ has constant $H = \mp \frac{1}{2\sqrt{K}}$.

\therefore Constant Gaussian curv \iff Constant mean curv. under the transformation of parallel surfaces.

7.5

Recall: $\begin{cases} K > 0 & \text{elliptic} \\ K = 0 & \text{parabolic or planar} \\ K < 0 & \text{hyperbolic} \end{cases}$

Prop: If S is cpt. sfc, \exists point P of S w/ positive Gaussian curvature.
 closed and bounded.

Extreme Value Thm: If $f: K \rightarrow \mathbb{R}$, then $\exists p, q \in K$ s.t. $f(p) \leq f(x) \leq f(q) \forall x \in K$.

IF: Let $f(\vec{\sigma}) = \|\vec{\sigma}\|^2$. $\exists P \in S$ attaining $\max \implies S$ inside sphere of radius $\|\vec{p}\|$.

But the tangent spaces of S , sphere \mathcal{S} are the same...

\vec{r} unit speed curve $\implies f(\vec{r})$ achieves min at $t=0$ thru P at $t=0$

$\implies \frac{d}{dt} f(\vec{r}(t)) = 0, \frac{d^2}{dt^2} f(\vec{r}(t)) \leq 0 \implies \frac{d}{dt} \|\vec{r}\|^2 = 0, \frac{d^2}{dt^2} \|\vec{r}\|^2 \leq 0$

$\implies \vec{r} \cdot \vec{r}' = 0, 2\vec{r} \cdot \vec{r}'' + 2\vec{r}' \cdot \vec{r}' = 0$ or $\vec{r} \cdot \vec{r}'' + 1 \leq 0$

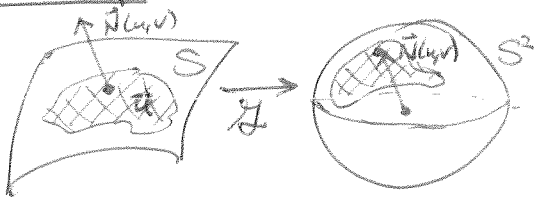
So $\vec{p} = \vec{r}(0)$ is \perp tangent plane of S at P .

We have $\vec{N} = \pm \frac{\vec{p}}{\|\vec{p}\|}$. But $k_n = \vec{r}''(0) \cdot \vec{N} = \pm \frac{\vec{r}''(0) \cdot \vec{p}}{\|\vec{p}\|} \leq \frac{1}{\|\vec{p}\|}$ so $K_n = \frac{-1}{\|\vec{p}\|}$ or $\geq \frac{1}{\|\vec{p}\|}$, for all curves.

Now Cor 6.2 $\implies K \geq \frac{1}{\|\vec{p}\|^2} > 0$ at P .



76 Gauss Map



// Gauss Map, can be defined for any orientable surface.

Recall: For \vec{v} unit speed plane curve, $K_s = \frac{d\varphi}{ds}$ for fixed angle φ
← st. patch.

Link: Let $R \in \mathcal{U}$. Then rate of change of \vec{N} per unit area $\approx \frac{\text{area } \vec{N}(R)}{\text{area } \vec{\sigma}(R)} \approx \frac{A_{\vec{N}}(R)}{A_{\vec{\sigma}}(R)}$
 where $A_{\vec{\sigma}}(R) = \iint_R \|\sigma_u \times \sigma_v\| du dv$

Theorem: Let $\vec{\sigma}: \mathcal{U} \rightarrow \mathbb{R}^3$ be stc, $(u_0, v_0) \in \mathcal{U}$, $\delta > 0$ s.t. $R_\delta(u_0, v_0) \subset \mathcal{U}$.
 Then $\lim_{\delta \rightarrow 0} \frac{A_{\vec{N}}(R_\delta)}{A_{\vec{\sigma}}(R_\delta)} = |K|$.



Pf: Ratio is $\approx \frac{\|\vec{N}_u \times \vec{N}_v\|}{\|\sigma_u \times \sigma_v\|} \Delta u \Delta v$

But $\vec{N}_u \times \vec{N}_v = (a\sigma_u \times b\sigma_v) \times (c\sigma_u \times d\sigma_v) = (ad-bc)\sigma_u \times \sigma_v = \det W \sigma_u \times \sigma_v = K \sigma_u \times \sigma_v$.

Precisely, we have Ratio = $\frac{\int_{R_\delta} |K| \|\sigma_u \times \sigma_v\| du dv}{\int_{R_\delta} \|\sigma_u \times \sigma_v\| du dv}$.

But given $\epsilon > 0$, choose $\delta > 0$ s.t. $|K(u,v) - K(u_0, v_0)| < \epsilon$ for all pts in R_δ .
 Then $|K| - \epsilon < |K| < |K| + \epsilon$

so $\int_{R_\delta} (|K| - \epsilon) \|\sigma_u \times \sigma_v\| du dv < \int_{R_\delta} |K| \|\sigma_u \times \sigma_v\| du dv < \int_{R_\delta} (|K| + \epsilon) \|\sigma_u \times \sigma_v\| du dv$

so $|K| - \epsilon < \text{Ratio} < |K| + \epsilon$

Since this is true for all ϵ , $\lim_{\delta \rightarrow 0} \text{Ratio} = |K|$. // Can also check the signs!

Ex Application: Plane $\Rightarrow \vec{N}(R)$ has zero area $\Rightarrow K=0$.

Cylinder $\Rightarrow \vec{N}(R)$ 1-dim $\Rightarrow K=0$.

Sphere $\Rightarrow \vec{N}(R)$ has area dependent only on radius of sphere \Rightarrow curvature $\frac{1}{r^2}$.

Ex: Torus:



Part of positive curvature covers the entire sphere exactly once \Rightarrow maps to whole sphere w/ area $4\pi r^2$.

More on the Gauss Map

$\mathcal{W} = d\mathcal{H}$ differential. What is a differential?
 → matrix of partials

$$\mathcal{H}: S \rightarrow S^2$$

$d\mathcal{H}_p: T_p(S) \rightarrow T_{\mathcal{H}(p)}(S^2)$ can be taken as a map $T_p(S) \rightarrow T_p(S)$ since tangent spaces are parallel.



$d\mathcal{H}_p$ measures how quickly ~~tangent~~ ^{normal} vectors diverge!

In local coords, we have $\mathcal{H}(u,v) = \frac{\vec{\sigma}_u \times \vec{\sigma}_v}{\|\vec{\sigma}_u \times \vec{\sigma}_v\|}$. But $\vec{N}_u = a\vec{\sigma}_u + b\vec{\sigma}_v$
 $\vec{N}_v = c\vec{\sigma}_u + d\vec{\sigma}_v$

So for a tangent vector $\begin{pmatrix} u' \\ v' \end{pmatrix}$, we have $d\mathcal{H}\begin{pmatrix} u' \\ v' \end{pmatrix} = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} u' \\ v' \end{pmatrix} = \mathcal{W}\begin{pmatrix} u' \\ v' \end{pmatrix}$.

Therefore, \mathcal{W} is the differential of the Gauss map $\mathcal{W}_p = d\mathcal{H}_p$.

And we can say $K = \det(d\mathcal{H}_p)$, $H = \frac{1}{2} \text{tr}(d\mathcal{H}_p)$, K_i are the eigenvalues of $d\mathcal{H}_p$.